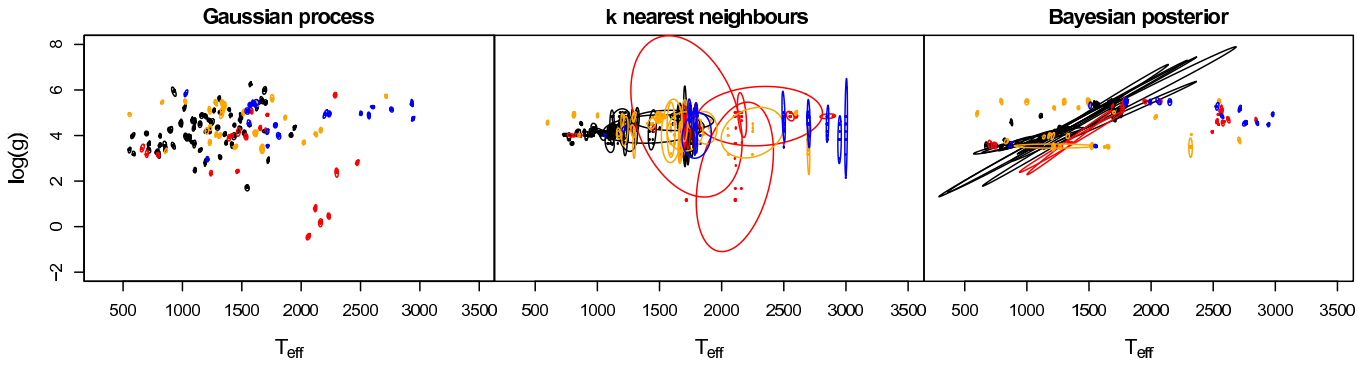
Gaussian process
k nearest neighbours
Bayesian posterior
log(g)
−2
0
2
4
6
8
500
1000
1500
2000
2500
3000
3500
T_eff