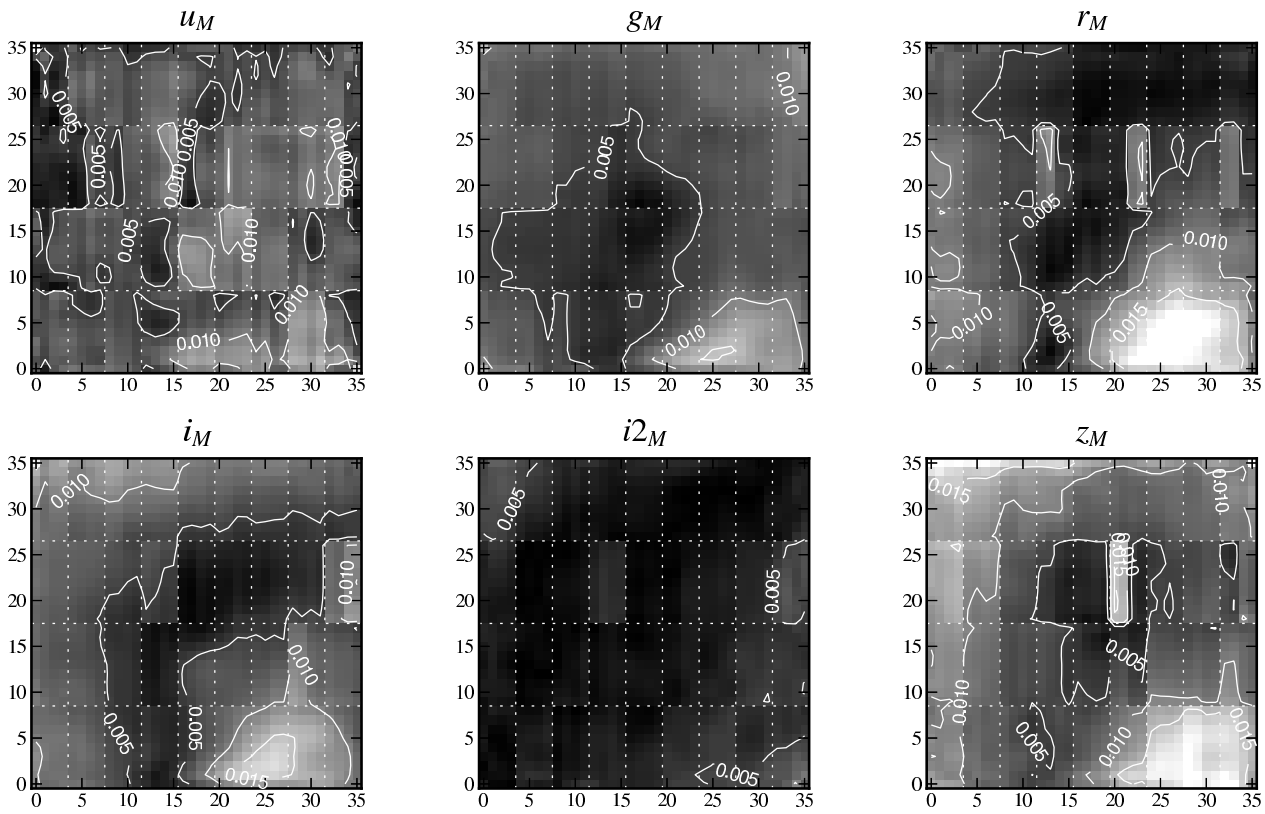
u_M
g_M
r_M
i_M
$i2_M$
z_M