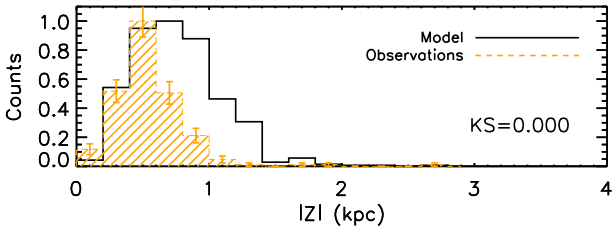
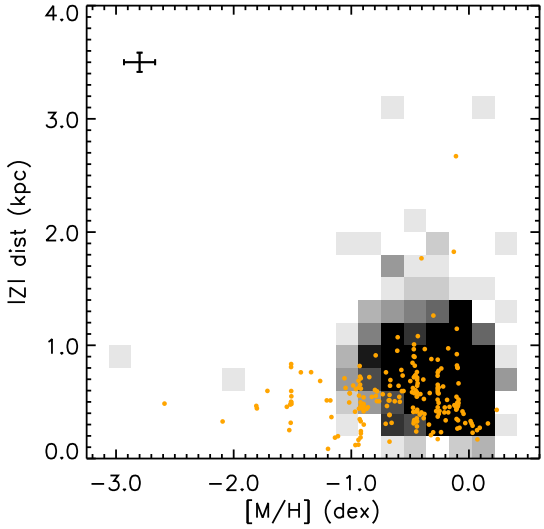
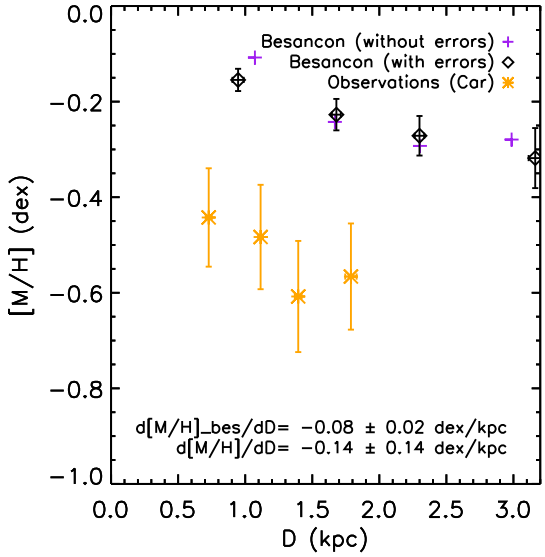

Counts
Model
Observations
KS=0.000
|Z| (kpc)


|Z| dist (kpc)
[M/H] (dex)


Besancon (without errors)
Besancon (with errors)
Observations (Car)
d[M/H]_bes/dD= −0.08 ± 0.02 dex/kpc
d[M/H]/dD= −0.14 ± 0.14 dex/kpc
[M/H] (dex)
D (kpc)