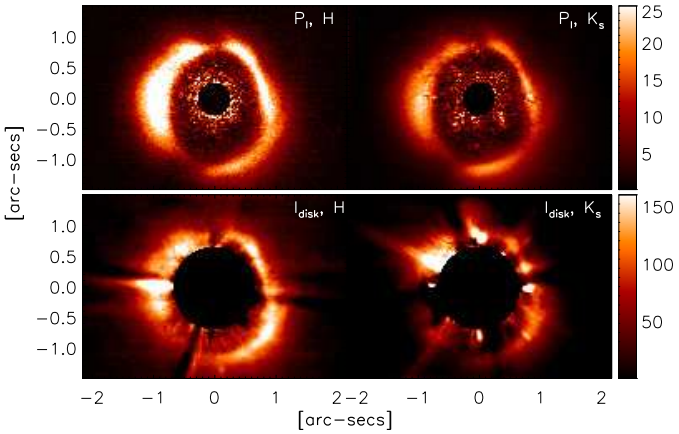
P_I, H
P_I, K_s
I_disk, H
I_disk, K_s
[arc−secs]
[arc−secs]
1.0
0.5
0.0
−0.5
−1.0
−2
−1
0
1
2
25
20
15
10
5
150
100
50