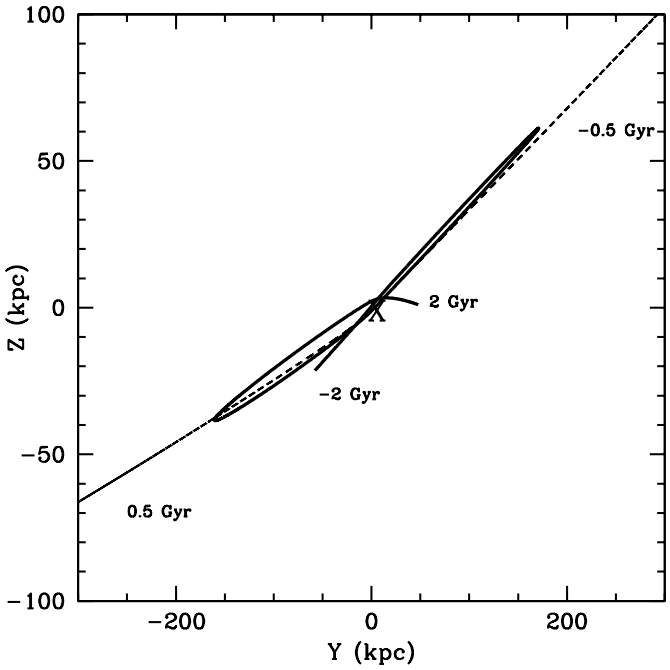
100
50
0
−50
−100
Z (kpc)
−200
0
200
Y (kpc)
−0.5 Gyr
2 Gyr
−2 Gyr
0.5 Gyr