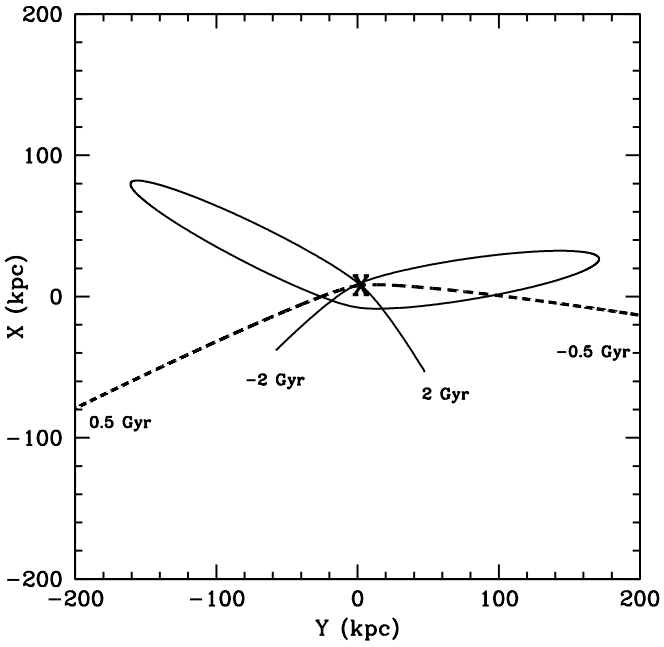
200
100
0
−100
−200
X (kpc)
−200
−100
0
100
200
Y (kpc)
−0.5 Gyr
−2 Gyr
2 Gyr
0.5 Gyr