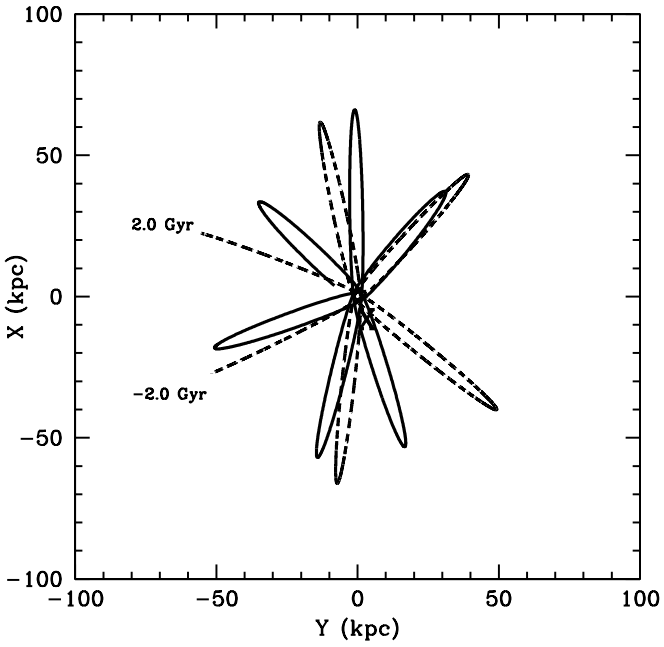
100
50
0
−50
−100
X (kpc)
−100
−50
0
50
100
Y (kpc)
2.0 Gyr
−2.0 Gyr