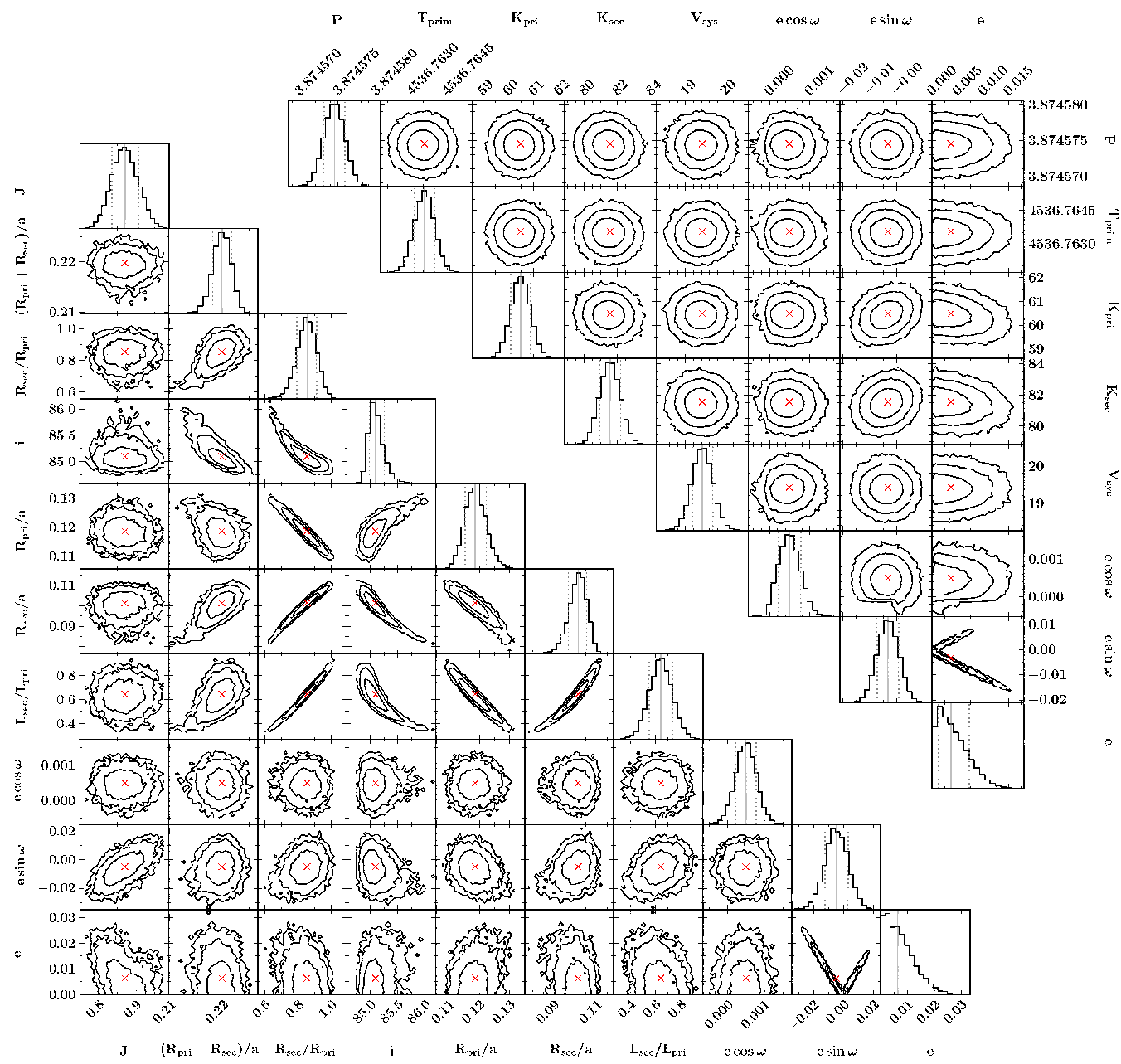
P
T_prim
K_pri
K_sec
V_sys
e cos ω
e sin ω
e
J
(R_pri + R_sec)/a
R_sec/R_pri
i
R_pri/a
R_sec/a
L_sec/L_pri