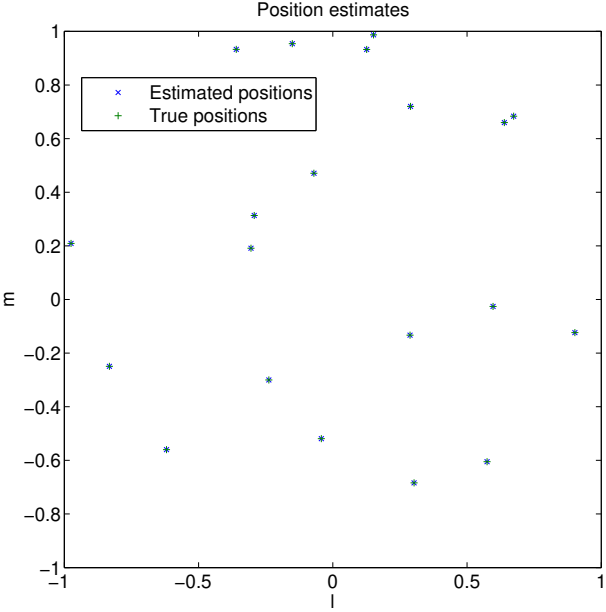
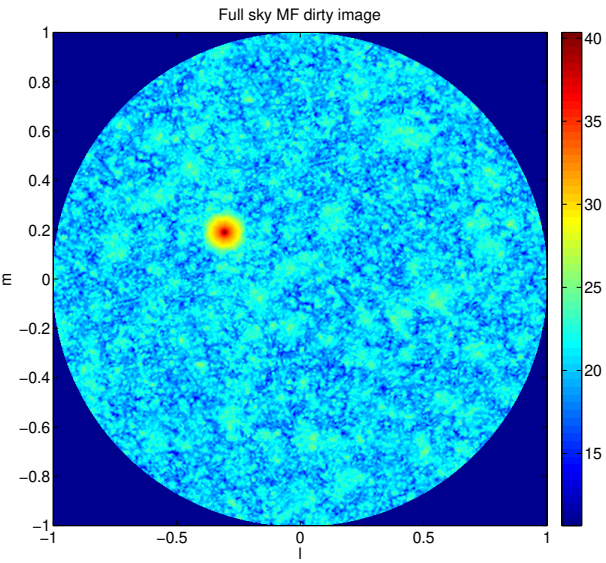

Position estimates
Estimated positions
True positions
m
l
1
0.8
0.6
0.4
0.2
0
−0.2
−0.4
−0.6
−0.8
−1
−1
−0.5
0
0.5
1

(a)


Full sky MF dirty image
m
l
40
35
30
25
20
15
1
0.8
0.6
0.4
0.2
0
−0.2
−0.4
−0.6
−0.8
−1
−1
−0.5
0
0.5
1

(b)